

# Computation with Gröbner bases over finite fields

Elisa Gorla

Université de Neuchâtel, Switzerland

First European training school in Network Coding  
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# Outline

Existence

Finiteness

Number of solutions

Computation of the solutions

# When does a system have solutions?

## Question

Given  $f_1, \dots, f_s \in \mathbb{F}[x_1, \dots, x_n]$ , when does the following system have solutions in  $\mathbb{F}^n$ ?

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- ▶ If  $f_1, \dots, f_s$  have degree 1, we can decide if there are solutions and solve the system by Gaussian elimination.
- ▶ If  $n = 1$ , compute  $f = \gcd(f_1, \dots, f_s)$ . The solutions of the system are exactly the solutions of  $f = 0$ . They are at most  $\deg f$ .

# Polynomial ideals and solutions over the algebraic closure

Write  $\mathcal{Z}_{\mathbb{F}}(f_1, \dots, f_s)$  for the set of solutions of  $f_1 = \dots = f_s = 0$ .

## Example

$f = x^2 + 1$  has  $\mathcal{Z}_{\mathbb{R}}(f) = \emptyset$  but  $\mathcal{Z}_{\mathbb{C}}(f) = \{\pm i\}$ .

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Solving the system  $f_1 = \dots = f_s = 0$  is the same as computing the set of zeros of the **ideal**  $I = (f_1, \dots, f_s) = \{\sum_{i=1}^s g_i f_i \mid g_i \in \mathbb{F}[x_1, \dots, x_n]\}$  :

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## Theorem (Hilbert's Nullstellensatz)

$I = (f_1, \dots, f_s) \subseteq \mathbb{F}[x_1, \dots, x_n]$ .  $\mathcal{Z}_{\overline{\mathbb{F}}}(f_1, \dots, f_s) = \emptyset$  iff  $I = (1)$ .



# When does a system have finitely many solutions?

Let  $\mathcal{S}$  denote the system  $f_1 = \dots = f_s = 0$  and  
 $I = (f_1, \dots, f_s) \subset \mathbb{F}[x_1, \dots, x_n] = P$ .

## Theorem (Finiteness Criterion)

*The following are equivalent:*

1.  $\mathcal{S}$  has finitely many solutions in  $\overline{\mathbb{F}}^n$ .
2. The set of solutions  $\mathcal{Z}(I)$  is zero-dimensional, i.e.,  $\dim(P/I) = 0$ .
3. For  $i = 1, \dots, n$  we have  $I \cap \mathbb{F}[x_i] = (g_i) \neq (0)$ .

## Remark

- ▶ 1.-3. imply that  $\mathcal{S}$  has finitely many solutions over  $\mathbb{F}$ .
- ▶ The number of solutions of  $\mathcal{S}$  is at most  $\deg(g_1) \cdots \deg(g_n)$ .

# How many solutions does a system have?

## Example

Let  $f_1 = x_1^2 + x_2 + x_3 - 1$ ,  $f_2 = x_1 + x_2^2 + x_3 - 1$ ,  $f_3 = x_1 + x_2 + x_3^2 - 1$ ,  
 $I = (f_1, f_2, f_3) \subseteq P = \mathbb{F}_{23}[x_1, x_2, x_3]$ .

For all  $i = 1, 2, 3$  we have

$$I \cap \mathbb{F}_{23}[x_i] = 6x_i^6 - x_i^4 + x_i^3 - 6x_i^2 =: g(x_i).$$

$g(x) = 0$  has solutions  $x = 0, 1, 4, 17$ .

By substituting into the original system, we see that of the 64 possible combinations, only the following 5 are solutions:

$$(1, 0, 0), (0, 1, 0), (0, 0, 1), (4, 4, 4), (17, 17, 17).$$

# Exact number of solutions

If a polynomial  $f$  vanishes on a point then also  $\text{sqfree}(f)$  vanishes on that point. Hence  $\mathcal{Z}(I)$  stays the same if we add the the squarefree parts of some polynomials in  $I$ .

## Definition

$\mathbb{F}$  a finite field. The **radical** of  $I$  is  $\sqrt{I} = I + (\text{sqfree}(g_1), \dots, \text{sqfree}(g_n))$ .

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### Theorem (Exact number of solutions)

Let  $\mathbb{F}$  a finite field, let  $I$  be a zero-dimensional ideal. The number of solutions  $\mathcal{Z}_{\mathbb{F}}(I)$  is equal to  $\dim_{\mathbb{F}}(P/\sqrt{I})$ .

## Normal position

The **Lex method** extends the Gaussian elimination method.

In order to solve a system  $f_1 = \dots = f_s = 0$ , we compute

$$(g_i) = I \cap \mathbb{F}[x_j]$$

for  $i = 1, \dots, n$ , then

$$\sqrt{T} = I + (\text{sqfree}(g_1), \dots, \text{sqfree}(g_n)).$$

### Definition

$\sqrt{T}$  is in **normal  $x_n$ -position** if any two zeroes  $(a_1, \dots, a_n)$ ,  $(b_1, \dots, b_n) \in \mathcal{Z}(\sqrt{T})$  have  $a_n \neq b_n$ .

If  $\mathbb{F}$  has enough elements, a linear transformation can be found which puts  $\sqrt{T}$  in normal  $x_n$ -position.

## Solutions of the polynomial system

## Theorem (The Shape Lemma)

Let  $\mathbb{F}$  be a finite field, let  $\sqrt{I}$  be a zero-dimensional ideal in normal  $x_n$ -position, let  $h_n = \text{sqfree}(g_n) \in \mathbb{F}[x_n]$  be monic,  $(h_n) = \sqrt{I} \cap \mathbb{F}[x_n]$ , let  $d = \deg(h_n)$ .

1. The reduced Lex Gröbner basis of the ideal  $\sqrt{I}$  is of the form

$$\{x_1 - h_1, \dots, x_{n-1} - h_{n-1}, h_n\},$$

where  $h_1, \dots, h_{n-1} \in \mathbb{F}[x_n]$ .

2.  $h_n$  has  $d$  distinct zeros  $\alpha_1, \dots, \alpha_d \in \overline{\mathbb{F}}$ , and the set of zeros of  $I$  is  $\mathcal{Z}(I) = \{(h_1(\alpha_i), \dots, h_{n-1}(\alpha_i), \alpha_i) \mid i = 1, \dots, d\}$ .

# Gröbner bases

Choose an ordering on the set of monomials of  $\mathbb{F}[x_1, \dots, x_n]$ , e.g., the **Lex order** is given by

$$x_1^{a_1} \cdots x_n^{a_n} > x_1^{b_1} \cdots x_n^{b_n} \Leftrightarrow (a_1 - b_1, \dots, a_n - b_n) >_{\text{Lex}} (0, \dots, 0).$$

## Definition

The set  $G = \{k_1, \dots, k_t\}$  is a **Gröbner basis** of  $I = (f_1, \dots, f_s)$  if division of any polynomial  $f \in I$  by  $G$  gives remainder 0.



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$$P = \mathbb{Z}_3[x_1, x_2], \quad f_1 = x_1 x_2^2 - x_2^3, \quad f_2 = x_1^2 + x_2^2,$$

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Gröbner bases can be computed via Buchberger's algorithm.